# **Supporting Information:**

## Low-Frequency (1/*f*) Noise in Nanocrystal Field-Effect Transistors

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#### Discussion

## Calculation of Carrier Mobility for Saturation and Linear regimes<sup>1</sup>

In the linear regime ( $V_{GS}$ - $V_T$  >  $V_{DS}$  > 0), carrier mobility is determined by

$$\mu_{LIN} = \frac{1}{C_{ox} \frac{L}{W} V_{DS}} \left( \frac{\partial I_D}{\partial V_{GS}} \right)$$

where  $C_{ox}$  is oxide capacitance, L is channel length, and W is channel width. In the saturation regime ( $V_{DS} > V_{GS} - V_T > 0$ ), carrier mobility is determined by

$$\mu_{SAT} = \frac{2}{C_{ox} \frac{L}{W}} (\frac{\partial I_D^{1/2}}{\partial V_{GS}})^2$$

## Length Dependence of $S_I/I_D^2$

For a homogenous semiconductor, the noise expression<sup>2,3</sup> can be presented as

$$\frac{S_I}{I_D^2} = \frac{S_R}{R^2} = \frac{S_{Rchannel} + S_{Rcontact}}{(R_{channel} + R_{contact})^2} = \frac{\alpha}{Nf} \quad (1)$$

where  $S_{Rchannel}$  and  $S_{Rcontact}$  represent two uncorrelated noise sources and  $R_{channel}$  and  $R_{contact}$  are the channel and contact resistances. Using  $\frac{S_R}{R^2} = \frac{\alpha}{Nf}$  relationship,  $S_{Rchannel} = \frac{\alpha_{channel}R_{channel}^2}{N_{channel}f}$ and  $S_{Rcontact} = \frac{\alpha_{contact}R_{contact}^2}{N_{contact}f}$  can be derived, where N is defined as free carriers in the channel or contact region. The carrier concentrations and resistances in the channel or contact regions are related to the transistor channel length (L) and width (W), and can be simplified as  $N_{ch} \propto L \times W$ ,  $N_{contact} \propto \frac{1}{W}$ ,  $R_{ch} \propto \frac{L}{W}$  and  $R_{contact} \propto \frac{1}{W}$ .<sup>2,3</sup> Depending on the magnitude of each term, Equation 1 can be simplified into four possible expressions.

$$\begin{aligned} R_{channel} > R_{contact} , S_{Rchannel} > S_{Rcontact} & \frac{S_I}{I_D^2} = \frac{S_R}{R^2} = \frac{S_{Rchannel}}{R_{channel}^2} \propto \frac{1}{L \times W} \\ R_{channel} > R_{contact} , S_{Rcontact} > S_{Rchannel} & \frac{S_I}{I_D^2} = \frac{S_R}{R^2} = \frac{S_{Rcontact}}{R_{channel}^2} \propto \frac{W}{L^2} \\ R_{contact} > R_{channel} , S_{Rchannel} > S_{Rcontact} & \frac{S_I}{I_D^2} = \frac{S_R}{R^2} = \frac{S_{Rcontact}}{R_{contact}^2} \propto \frac{L}{W} \\ R_{contact} > R_{channel} , S_{Rcontact} > S_{Rchannel} & \frac{S_I}{I_D^2} = \frac{S_R}{R^2} = \frac{S_{Rcontact}}{R_{contact}^2} \propto \frac{L}{W} \end{aligned}$$

With the assumption of a constant value of W or W/L, Table 2 in the main text is derived.

### **Stretched Exponential Function**

Bias-stress effects are typically described by a stretched exponential function<sup>4,5</sup> as

$$\Delta V_T = (V_{GS} - V_{T0}) \{ 1 - exp \left[ - (t/_{\mathcal{T}})^{\beta} \right] \}$$
(2)

where  $\Delta V_T$  is threshold voltage (V<sub>T</sub>) shift under constant gate-source (V<sub>GS</sub>) and drain-source bias (V<sub>DS</sub>) for an extended period of time. V<sub>T0</sub> is the initial value of V<sub>T</sub>, t is the time the stress is applied, and  $\tau$  and  $\beta$  are fitting parameters. This equation can be converted to express bias-stress induced current degradation *via* current expressions for ideal thin-film transistors<sup>1</sup>. For example, the initial saturation current is

$$I = \frac{1}{2}\mu C_{ox} \frac{W}{L} (V_{GS} - V_{T0})^2 = k(V_{GS} - V_{T0})^2 \quad (3)$$

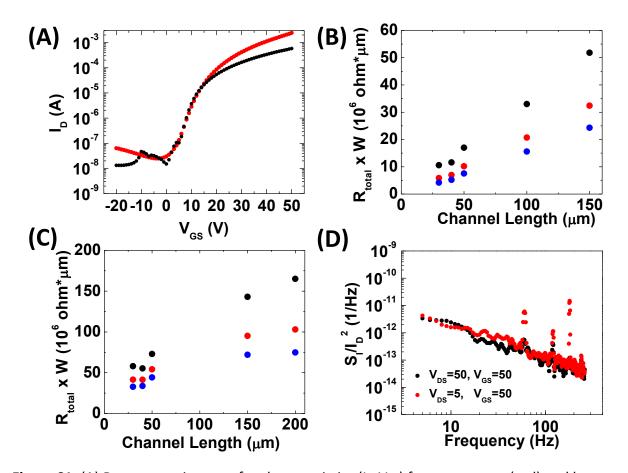
and changes to

$$I' = \frac{1}{2}\mu C_{ox} \frac{W}{L} [V_{GS} - (V_{T0} + \Delta V_T)]^2 = k [V_{GS} - (V_{T0} + \Delta V_T)]^2 \quad (4).$$

Expanding Equation (4) and using Equation (2) and (3), the saturation current degradation as a function of time is  $\frac{l'}{l} = \exp\left[-2\left(\frac{t}{\tau}\right)^{\beta}\right]$ . Using the initial linear current

$$I = \frac{1}{2}\mu C_{ox} \frac{W}{L} [2(V_{GS} - V_{T0})V_{DS} - V_{DS}^2]$$
 (5)

a similar function for linear current degradation can be derived as  $\frac{I'}{I} = \exp\left[-\left(\frac{t}{\tau}\right)^{\beta}\right]$ , assuming  $(V_{DS})^2$  is negligible. These two equations are applied to fit the time dependence of the drain-source current (I<sub>D</sub>) in Figure S5. It is obvious that encapsulated devices have orders of magnitude higher value of  $\tau$  than unencapsulated devices, suggesting encapsulated devices are more stable under bias-stress.

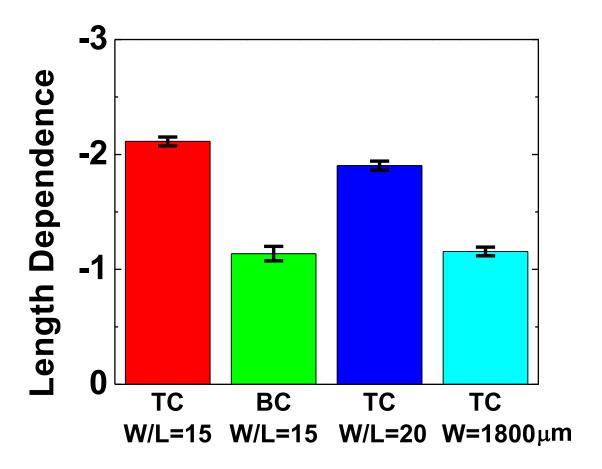


**Figure S1.** (A) Representative transfer characteristics ( $I_D$ - $V_{GS}$ ) for top-contact (red) and bottomcontact (black) devices, with L = 50 µm and measured at  $V_{DS}$  = 50 V. The contact ( $R_{contact}$ ) and channel ( $R_{channel}$ ) resistances are extracted from the total resistance ( $R_{total}$ ) as a function of channel length using the transmission line method for (B) top-contact and (C) bottom-contact devices respectively, collected at  $V_{GS}$  = 30 V (black),  $V_{GS}$  = 40 V (red), and  $V_{GS}$  = 50 V (blue). (D) A representative  $S_1/I_D^2$  vs frequency of a top-contact, L = 40 µm device measured in the saturation and linear regimes, showing that noise is weakly dependent on  $V_{DS}$ .

Channel Length (μm)	V <sub>GS</sub> = 40 V			V <sub>GS</sub> = 30 V		
	R <sub>total</sub> (Ω)	$\frac{\textbf{R}_{\text{contact}}}{\textbf{W}} \left( \boldsymbol{\Omega} \right)$	Mobility (cm²/Vs)	R <sub>total</sub> (Ω)	$\frac{\textbf{R}_{\text{contact}}}{\textbf{W}} \left( \boldsymbol{\Omega} \right)$	Mobility (cm²/Vs)
30	1.2x10 <sup>4</sup>	-2.2x10 <sup>3</sup>	19.73	2.1x10 <sup>4</sup>	-3.9x10 <sup>2</sup>	11.57
40	1.2x10 <sup>4</sup>	-1.6x10 <sup>3</sup>	19.45	2.1x10 <sup>4</sup>	-2.9x10 <sup>2</sup>	12.01
50	1.3x10 <sup>4</sup>	-1.3x10 <sup>3</sup>	17.29	2.1x10 <sup>4</sup>	-2.3x10 <sup>2</sup>	12.67
100	1.3x10 <sup>4</sup>	-6.6x10 <sup>2</sup>	15.75	2.2x10 <sup>4</sup>	-1.1x10 <sup>2</sup>	15.01
150	1.4x10 <sup>4</sup>	-4.4x10 <sup>2</sup>	15.01	2.2x10 <sup>4</sup>	-78.2	14.77

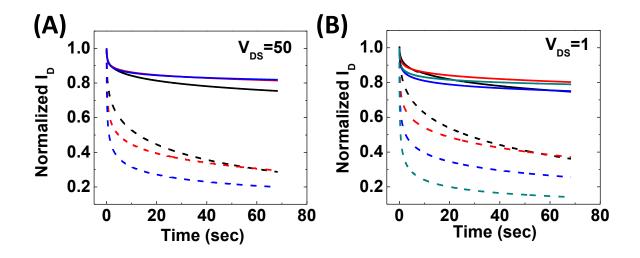
**Table S1.** Device resistances extracted by the transmission line method and carrier mobilities

for top-contact devices at  $V_{GS}$  = 40 V and  $V_{GS}$  = 30 V.

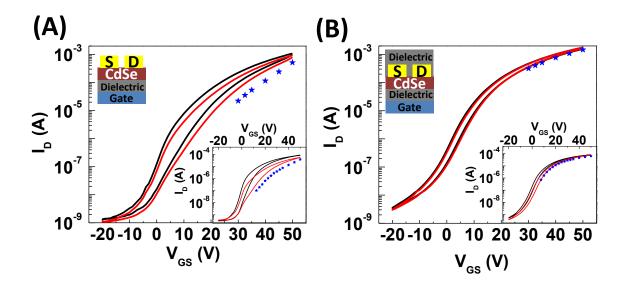


**Figure S2.** Statistics of the length dependence of  $S_1/I_D^2$  for different scaling of the device

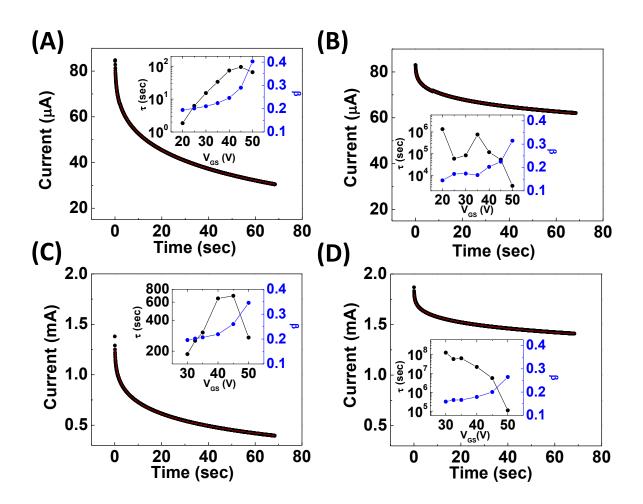
geometry.



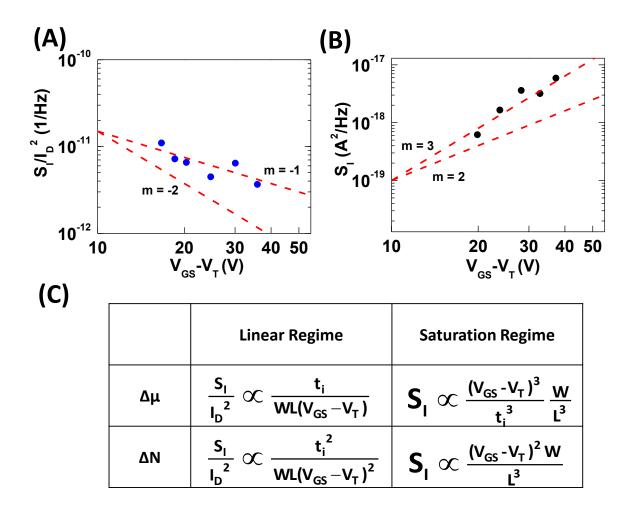
**Figure S3.** Time dependence of the normalized drain-source current ( $I_D$ ) measured under a voltage stress of (A)  $V_{DS} = 50$  V and (B)  $V_{DS} = 1$  V for an unencapsulated, top-contact device (dashed lines) and an  $AI_2O_3$ -encapsulated, top-contact device (solid lines), where  $V_{GS} = 50$  V (black),  $V_{GS} = 40$  V (red),  $V_{GS} = 30$  V (blue) and  $V_{GS} = 20$  V (green).



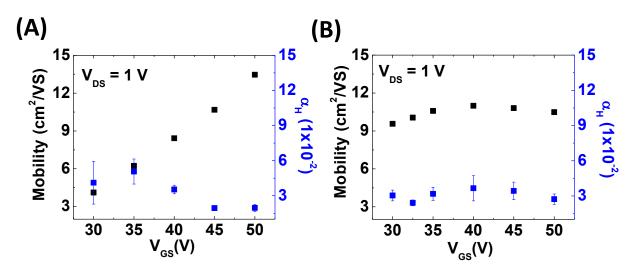
**Figure S4.** Device transfer characteristics  $I_D-V_{GS}$  for (A) an unencapsulated, top-contact and (B) an  $AI_2O_3$ -encapsulated, top-contact device at  $V_{DS} = 50$  V and  $V_{DS} = 1$  V (inset), where  $I_D-V_{GS}$  before (black) and after (red) noise collection are presented. The average stress current during noise collection is shown as blue stars at each applied bias and is the average of the current collected in Fig. S3 from 10 sec to the end of applied bias at 70 sec. Note: the calculated interface trap density from the subthreshold swing is 9.67 x  $10^{12}$  cm<sup>-2</sup> for (A) and 9.14 x  $10^{12}$  cm<sup>-2</sup> for (B).



**Figure S5.** Traces of I<sub>D</sub> as a function of time under voltage stress (black) and fits to a stretched exponential function (red) for (A) an unencapsulated, top-contact and (B) an Al<sub>2</sub>O<sub>3</sub>encapsulated, top-contact device under  $V_{DS} = 1 V$ ,  $V_{GS} = 50 V$  and for (C) an unencapsulated, top-contact device and (D) an Al<sub>2</sub>O<sub>3</sub>-encapsulated, top-contact device under  $V_{DS} = 50 V$ ,  $V_{GS} = 50 V$ . Insets in (A-D) show fitting parameters ( $\tau$  and  $\beta$ ) as a function of  $V_{GS}$ .



**Figure S6.** (A) Representative  $S_I/I_D^2 vs (V_{GS}-V_T)$  characteristics at a frequency of 10 Hz for an  $AI_2O_3$ -encapsulated device operated in the linear regime ( $V_{DS} = 1 V$ ). The slope fit for frequencies between 5 to 10 Hz in a step of 1 Hz is -0.9 ± 0.15. Slopes of -1 and -2 are drawn for reference. (B) Representative  $S_I vs (V_{GS}-V_T)$  at a frequency of 10 Hz for an  $AI_2O_3$ -encapsulated device operated in the saturation regime ( $V_{DS} = 50 V$ ). The slope fit for frequencies between 5 to 10 Hz is  $3.1 \pm 0.27$ . Slopes of 2 and 3 are drawn for reference. (C) Comparison of the  $S_I/I_D^2$  and  $S_I$  dependence on ( $V_{GS} - V_T$ ) for the Hooge ( $\Delta\mu$ ) and McWhorter ( $\Delta N$ ) models for devices operated in linear and saturation modes.<sup>6</sup>



**Figure S7.** Mobility and Hooge parameter ( $\alpha_H$ ) as a function of V<sub>GS</sub> when V<sub>DS</sub> = 1 V for (A) unencapsulated, top-contact and (B) Al<sub>2</sub>O<sub>3</sub>-encapsulated, top-contact devices.

#### Reference

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