Supporting Information for "Supersonic Impact Response of Polymer Thin Films via Large-Scale Atomistic Simulations"

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Simulation Methodology

Pre-processing and simulation of ballistic impacts on polymer thin films of polyethylene (PE) and polystyrene (PS) are conducted through a multistep process involving initial film construction, equilibration at melt temperature (600 K), annealment to room temperature (300 K), additional equilibration at room temperature, and finally impacts at various incident velocities. A stepwise overview of the simulation process is illustrated in Figure S1 for a PE thin film. The process is the same regardless of polymer type.
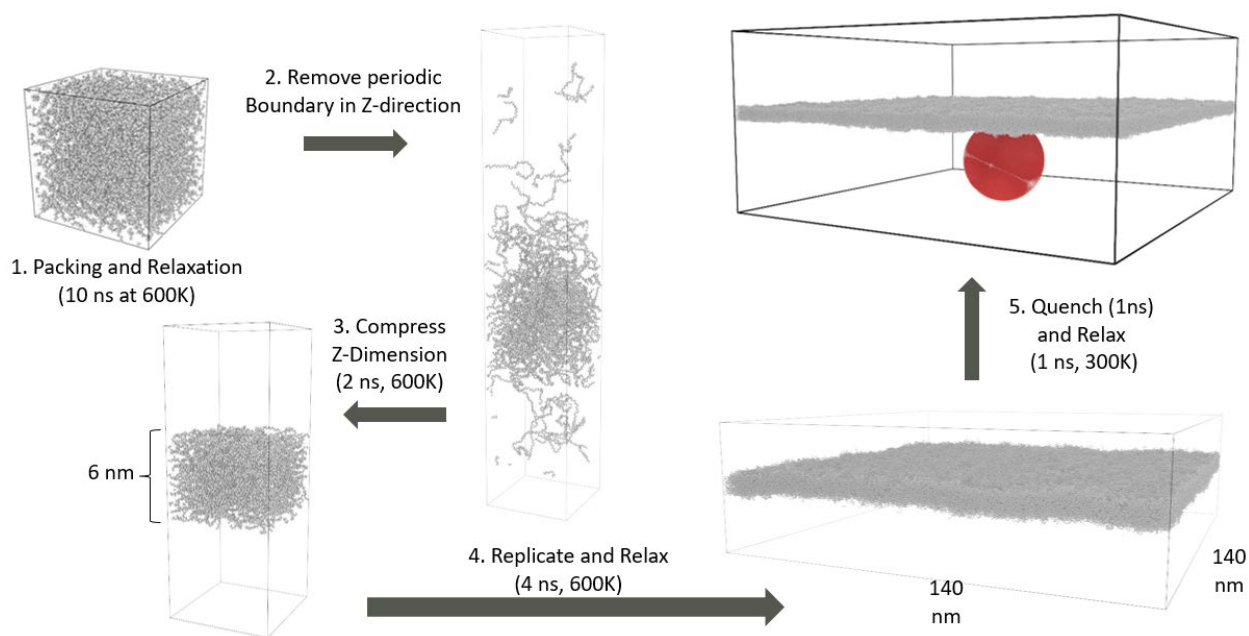

Figure S1. Stepwise overview of the simulation process of initial construction, relaxation, equilibration, and impact.

Initially, amorphous 3D periodic structures are packed using the web-based nanoHUB Polymer Modeler[1] tool with ten chains, each consisting of 1,000 carbon atoms, corresponding to molecular weights (M_n) of 14 kg/mol and 52.1 kg/mol for PE and PS, respectively. Terminal carbon atoms for each chain were terminated with hydrogen to achieve saturated structures. The amorphous structure files are exported to the Large-scale Atomic/Molecular Massively Parallel Simulator

26   (LAMMPS)[2] for minimization and equilibration with the DREIDING[3] potential. The structures

27   are equilibrated using a time step of 2 fs with a constant number of atoms, pressure, and

28   temperature (NPT) dynamics at zero pressure for 10 ns at a melt state of 600 K. This process of

29   equilibration was shown to fully relax the entanglements of PE systems[4]. For all thermostats and

30   barostats, dampening parameters of 100 and 1,000 time steps were used to dampen the temperature

31   and pressure respectively. Equilibration at melt temperature ensures the full relaxation of kinks

32   and entanglements and creates a well equilibrated initial structure. After initial equilibration,

33   periodicity of the z-direction is removed, maintaining 2D periodicity in the x and y dimensions;

34   and two fix wall commands in LAMMPS are used to push the polymer chains from the +z and –z

35   directions to the desired film thickness while allowing the lateral faces (x and y) to relax. The wall

36   is subsequently held at 600 K with NPT conditions in the x and y directions for 1 ns then removed

37   for 1 ns. This creates the stable thin film structure seen in Figure S1 at the end of Step 3. Next,

38   the stable thin films are replicated in the x and y dimensions to create the desired slab size (140

39   nm x 140 nm). Again, to relax the repeating segments, the large thin films are equilibrated at 600

40   K with NPT boundaries in the x and y directions for an additional 4 ns. Then the films are

41   quenched from 600 K to 300 K with a constant number of atoms, volume, and temperature (NVT)

42   dynamics over a time of 1 ns, then held at 300 K for an additional 1 ns. Finally, the thin films are

43   equilibrated for 0.5 ns at 300 K using either the AIREBO[5] or MEAM[6], potential producing well-

44   equilibrated thin film structures ready for impact simulations. The time step of 0.4 fs was used for

45   equilibration with AIREBO and MEAM as reactive potentials do not have explicitly defined bonds

46   and hydrogen atoms can be easily lost with elevated time steps.

47   After equilibration at 300 K, thin films were subjected to impact by a spherical projectile with a

48   range of initial supersonic and hypersonic velocities (0.5 – 5 km/s). A time step of 0.3 fs was used

49   to capture the atom displacement during impact. For the projectile, with a diameter of 30 nm, a

50   diamond lattice structure was used with a lattice constant of 7.14 Å and a bead mass of 96.1 g/mol.

51   Interactions between the projectile and the thin film are modeled by a typical 12-6 Lennard-Jones

52   potential with $\varepsilon_{lj} = 0.0085$ eV and $\sigma_{lj} = 3.46$ Å. The projectile is treated as a rigid body throughout

53   impact. These values have been investigated and found to have negligible effect on the impact

54   response, as the impactor is observed to stay rigid and friction between the impactor and thin films

55   is small during impact[7]. Areas around the edges of the thin film spanning 40 Å are fixed (via

56   setforce command) to mimic the clamping of the films similar to LIPIT experiments. Following

57   recommendations of previous ballistic impact MD simulations[7], a ratio of projectile radius (R) to

58   film thickness (t) of 2.5 was implemented, along with a thin film side length of eight projectile

59   radii. The projectile was placed close to the bottom surface of the films, and an upward initial

60   velocity was given to the projectile. An NVE (constant number of atoms, volume and energy)

61   ensemble is used to integrate the system dynamics during the impact event.

Post-Processing

Kinetic Energy, Temperature, and Pressure Calculation

64   The kinetic energy of the projectile is output every 10 time steps and is used to calculate the

65   energy absorbed by the thin films (E_P^*). E_P^* is defined as the loss of Kinetic Energy (KE) of the

66   projectile normalized by the mass of the thin film contained within the projectile's projected

67   impact area and is used as a metric to compare dissimilar materials. To calculate the film

68   temperature evolution, a temperature compute that removes the center-of-mass velocity (compute

69   temp/com) was used in LAMMPS to calculate the temperature of a group of atoms bound by the

70   projected area of the projectile. As the temperature around the impact site is inhomogeneous, there

71   is a spatial distribution of temperatures with higher temperatures located closer to the initial impact

72   site. Figure S2 illustrates the distribution of temperature emanating from the initial contact point

73   (black circle in Figure s2). The average temperature of the area bounded by the projectile diameter

74   was used in the manuscript. Similarly, a pressure compute of a group of atoms bounded by the

75   projected area of the projectile is defined. This computes a pressure*volume, therefore the

76   compute was divided by the volume of the thin film within the projected area (area*film thickness)

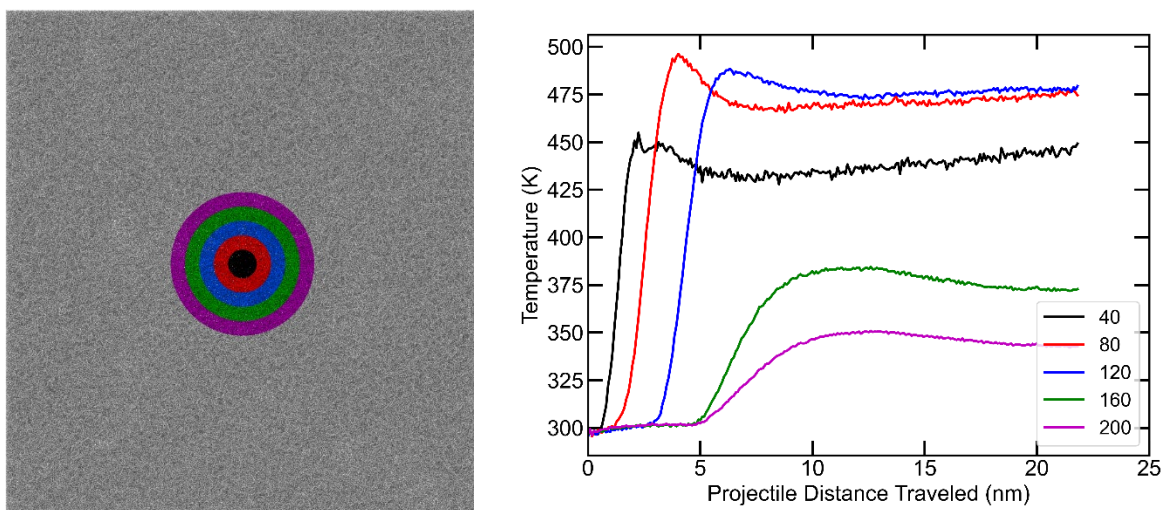77   to produce pressure.

78

79   Figure S2: Example of the spatial temperature distribution during a 1.5 km s^{-1} impact on PE

80   cooresponding to circlular areas with a radius of 40-200 Å.

81   **Film Characterization**

82   Careful characterization of the simulated thin films is important in order to properly establish

83   structure-property relationships. Figure S3 illustrates the density distributions of the thin films

84   along with the Voronoi volume profiles (atomic volume). The density distribution was calculated

85   by binning the thin film (100 bins) along the z-dimension (thickness) and determining the density

86   of each bin by totaling the atomic weight of the atoms within each bin divided by the bin volume.

87   The atomic volumes were calculated using the Voronoi Analysis feature of the Open Visualization

88   Tool (OVITO)[8] to calculate the local volume of each atom and then plotted against the z-coordinate

89   of the respective atom.

90   Using the density distribution in Figure S3, the average film density can be calculated by

91   averaging the density of each bin weighted by the number of atoms in each bin. Similarly, the

92   average film thickness can be determined by averaging the z-position of each bin weighted by the

93   number of atoms in each bin. This procedure produces estimated average film densities of 643 kg

94   m^{-3} and 789 kg m^{-3} and film thicknesses of 4.8 nm and 4.9 nm for PE and PS, respectively. Note,

95   by taking into account the near-surface lower density regions, the average film density is less than

96   the bulk densities that appear at the center of the films (approximately 750 kg m^{-3} and 945 kg m^{-}

97   ^{3}), and the average film thickness is slightly less than the target thickness of 6 nm. The PE

98   considered in this work is in the completely amorphous state, as crystallization times are too long

99   for MD simulations, which produces a density lower than experimentally observed semicrystalline

100   PE. From analysis of the Voronoi volume profiles, the films contain centralized well-packed

101   dense regions approximately 3-4 nm thick and then enter a transition region in which the local

102   atomic volume increases (density decreases) as the surface is approached. Free surfaces have a

103   strong influence on chain dynamics[9] by increasing chain mobility and lowering the entanglement

104   density. The effect of free surfaces are emphasized by the observed transition regions (decreasing

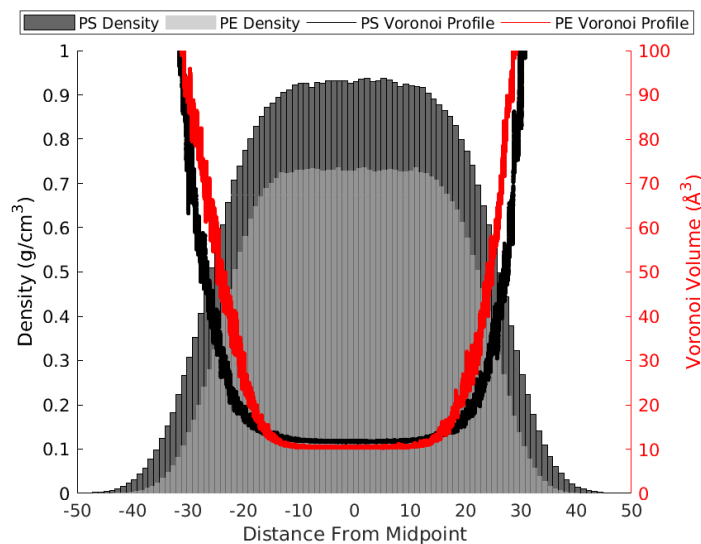105   density regions) in Figure S3 and is broader in PS.

Figure S3. Density and atomic Voronoi volume profiles of amorphous PS and PE thin films indicating bulk high-density regions at the film center and low- density transition regions near the surface.

Bond Scission and Entanglement Density Calculation

Again, proper characterization is a key step in analysis of mechanical properties of materials. For postprocessing the evolution of broken bonds, OVITO[8] is used to visualize the perforation at various points during impact. The create bonds OVITO modifier is used to calculate the number of bonds for each snapshot in time (based on neighbor cut of distance) and to determine the loss of bonds over the course of impact for each bond type. For this work, bonds between each different types of atoms can rupture. Here, C-H, C-C, and C-phenyl (Ph) bonds were observed to rupture during impact. The total number of ruptured bonds versus impact velocity is illustrated in Figure S4. For an estimate of the total energy dissipated through bond breaking, bond energies of 3.58 ev/bond were assumed for C-C and C-Ph bonds and 4.28 ev/bond were assumed for C-H bonds. By multiplying the bond energy by the number of broken bonds and normalizing by the total amount of energy dissipation, the contribution of bond scission to energy dissipation can be

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122   estimated as seen in Figure S4. Overall, the direct contribution of bond scission to energy

123   dissipation is very low.
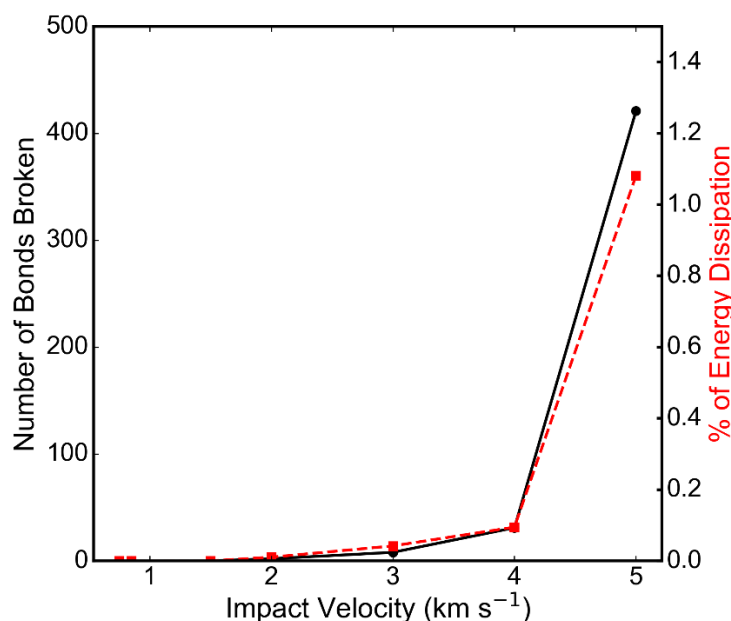
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125   **Figure S4.** Number of broken bonds in PS versus impact velocity. The red line depicts the % of

126   energy dissipation contributed through bond scission.

127   The entanglement density is quantified to study the influence of the entanglement density on

128   energy absorption, as the two are thought to be highly related. The number of entanglements is

129   not possible to count directly experimentally; therefore the ρ_e is typically estimated. In this work

130   we estimate the ρ_e from the molecular weight (M_n) and entanglement length (M_e) in the same

131   fashion as other experimental works[10,11] based on the entanglement network model of Bersted[12]:

132
$$\rho_e = \frac{2N_0\rho}{3M_c}\left(1 - \frac{M_c}{M_n}\right) \tag{1}$$

133   where N_0 is Avogadro's number, ρ is the film density, and $M_c \sim 2M_e$.

134   To maintain consistency between experiments and simulations, the simulated entanglement

135   molecular weight must be determined (density and M_n have been previously defined). The

136   complete connectivity network along the polymer backbone is easily defined by iterating through

137   the atoms sequentially, making the physical determination of entanglements possible. Several

138   methods exist, such as the Z1[13–15] and CReTA[16] methods, for topologically determining the actual

139   number of entanglements within the system. Use of reactive potentials can cause difficulties in

140   determining the connectivity network during deformation when bond scission and bond

141   reformation are likely, but determining the connectivity is typically trivial at the end of the

142   equilibration step before stress is applied to the system. The Z1 algorithm can give the number of

143   entanglements per chain along with additional data, such as the entanglement length. The ρ and

144   M_n for the model PS and PE were given earlier, and the M_e (2.3 and 25.8 kg mol^{-1} for PE and PS)

145   is found using the Z1 algorithm to determine the entanglement length of the given system.

Comparison of AIREBO and MEAM Potentials

147   In order to investigate the influence of bond breaking vs. disentanglement, a reactive (bond

148   breaking/forming) atomistic potential is required. Three well suited options exist: AIREBO[5],

149   MEAM[6], and Reactive Force Field (ReaxFF)[17]. ReaxFF is highly accurate; however, it incurs the

150   highest computational burden and is about an order of magnitude slower than AIREBO or MEAM.

151   Due to the size of the system and the already staggering computational undertaking, ReaxFF was

152   not considered for further testing. MEAM has been used successfully to study high-rate

153   deformation in PE[4] and is arguably more accurate than AIREBO. The pitfall for MEAM is that

154   currently only saturated polymers are possible to simulate, which eliminates the MEAM for

155   modeling PS. AIREBO is a computationally efficient reactive potential that has been successfully

156   used to model both PE[18] and PS[19].
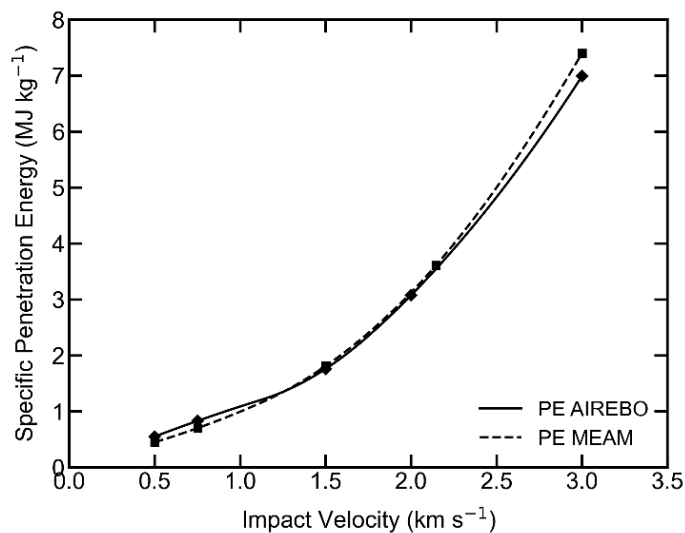
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Figure S5. Comparison of the specific penetration energy prediction for AIREBO and MEAM

potentials.

160   Impact simulations were conducted comparing the AIREBO and MEAM potentials specifically

161   for use in studying high-rate impacts in PE thin films. Figure S5 illustrates the specific penetration

162   energy (E_p^*) vs. impact velocity (V_i) response. Both potentials produce almost identical E_p^* vs. V_i

163   curves and are computationally similarly efficient. However, discrepancies arise when the fracture

164   behaviors at high velocities are compared. Figure S6 compares the impact responses of PE for the

165   AIREBO and MEAM potential at various impact velocities. At low velocities (<1.5 km s^{-1}), the

166   penetration behaviors are very similar. However, at higher velocities (> 3 km s^{-1}) significant

167   degradation is observed in PE using the MEAM potential due to adiabatic heating, resulting in

168   elevated film temperatures (~3000K) and severe bond disassociation of C-C (chain scission) and

169   C-H (dehydrogenation) bonds. This thermal degradation is not captured with AIREBO, possibly

170   due to a high C-C dissociation energy[6]. MEAM has also been shown to underpredict the heat of

171   reaction involving C-C and C-H bonds compared to AIREBO[20], which most likely causes MEAM

172 to predict lower thermal degradation temperature. Therefore, it appears that AIREBO may slightly

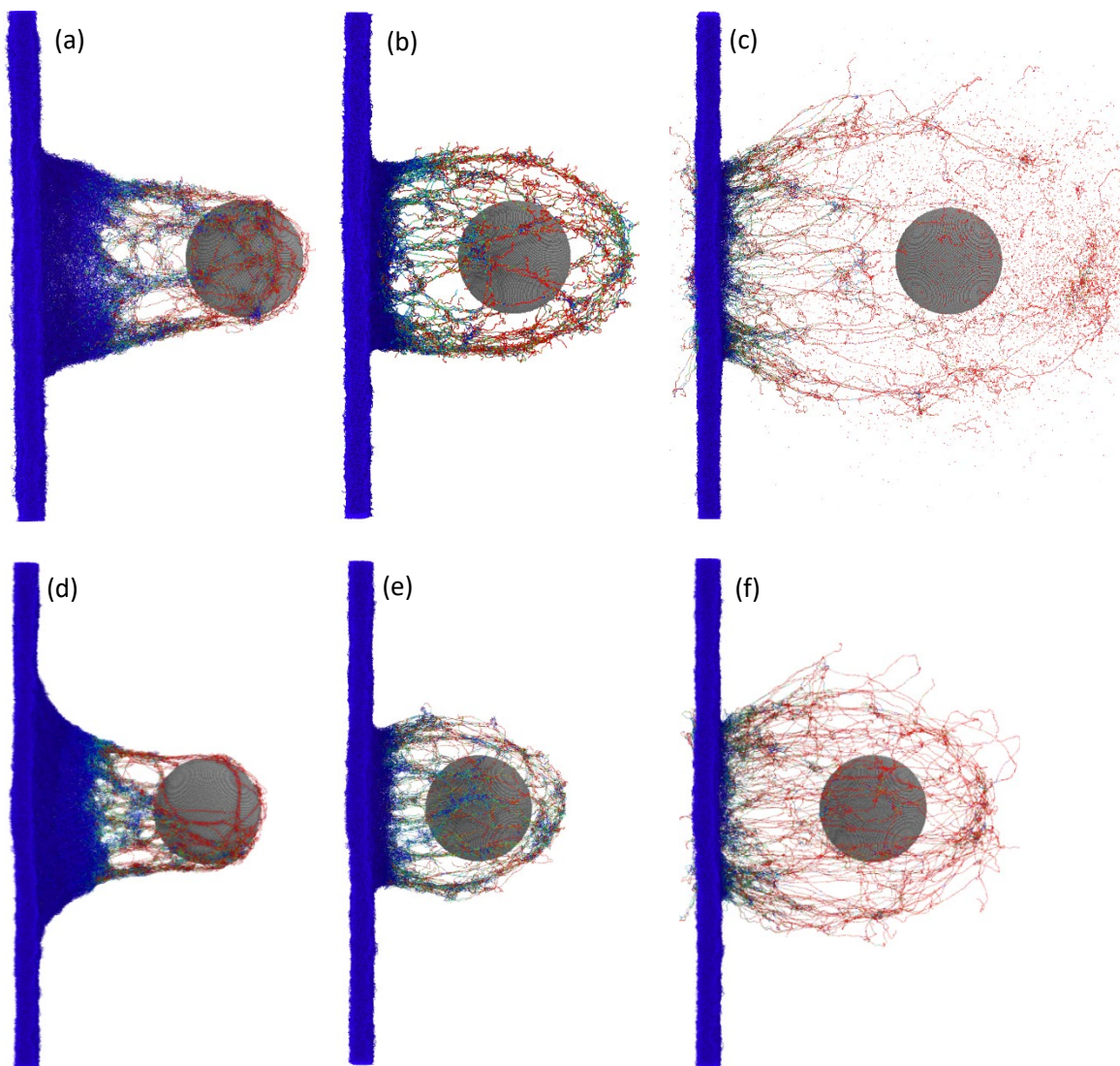173 underpredict degradation while MEAM slightly overpredicts degradation.

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176 **Figure S6.** Snapshots of the ballistic failure modes for amorphous polyethylene using the (a-c)

177 MEAM potential and (d-f) AIREBO potential impacted at (a,d) 0.75 km s^{-1}, (b,e) 1.5 km s^{-1}, and

178 (c,f) 3 km s^{-1} illustrating similar ballistic penetration responses for both potentials at low velocity

179 while only the MEAM captures temperature degradation at elevated velocity (c).

180 Degradation is a complex property to capture using MD, and simulations have been shown to be

181 highly influenced by the rate of temperature change[21], leading to overprediction of degradation

11

182   temperatures. Illustrated in Figure S7, temperatures predicted by AIREBO span several thousand

183   degrees. Hence, most of the analysis herein focuses on the supersonic impact regime before

184   temperature degradation occurs.   Additionally, for the ultrathin films studied, capturing the

185   degradation at hypersonic velocities is not critical, as the projectile quickly passes through the film

186   and energy is quickly dissipated (i.e., the projectile velocities decreases) before thermal

187   degradation occurs (as observed with MEAM), hence not influencing the resulting E_p^* (Figure S5).

188   Thus, even at higher impact velocities the specific penetration energies are nearly the same for

189   AIREBO and MEAM. For much thicker films this could become an issue, as the projectile may

190   not penetrate completely and degraded chains will be more impactful, and will need further

191   investigation. One last point to consider is that the degradation point could be shifted due to the

192   increase in degradation temperature seen in both PE and PS under high pressure[22]. Hence,

193   polymers can still absorb tremendous amounts of energy during hypervelocity impacts, even

194   though degradation occurs; and hydrocarbon based polymers, such as ultra-high molecular weight

195   PE, have been suggested for use as shielding in aerospace applications[23].

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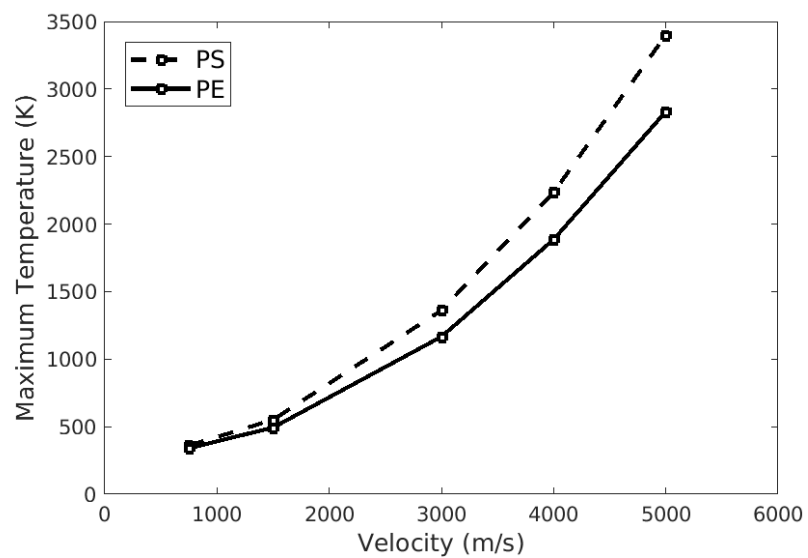
Figure S7: Maximum temperatures achieved during impact versus impact velocity for the AIREBO potential.

Additional Visualizations of Projectile Penetration
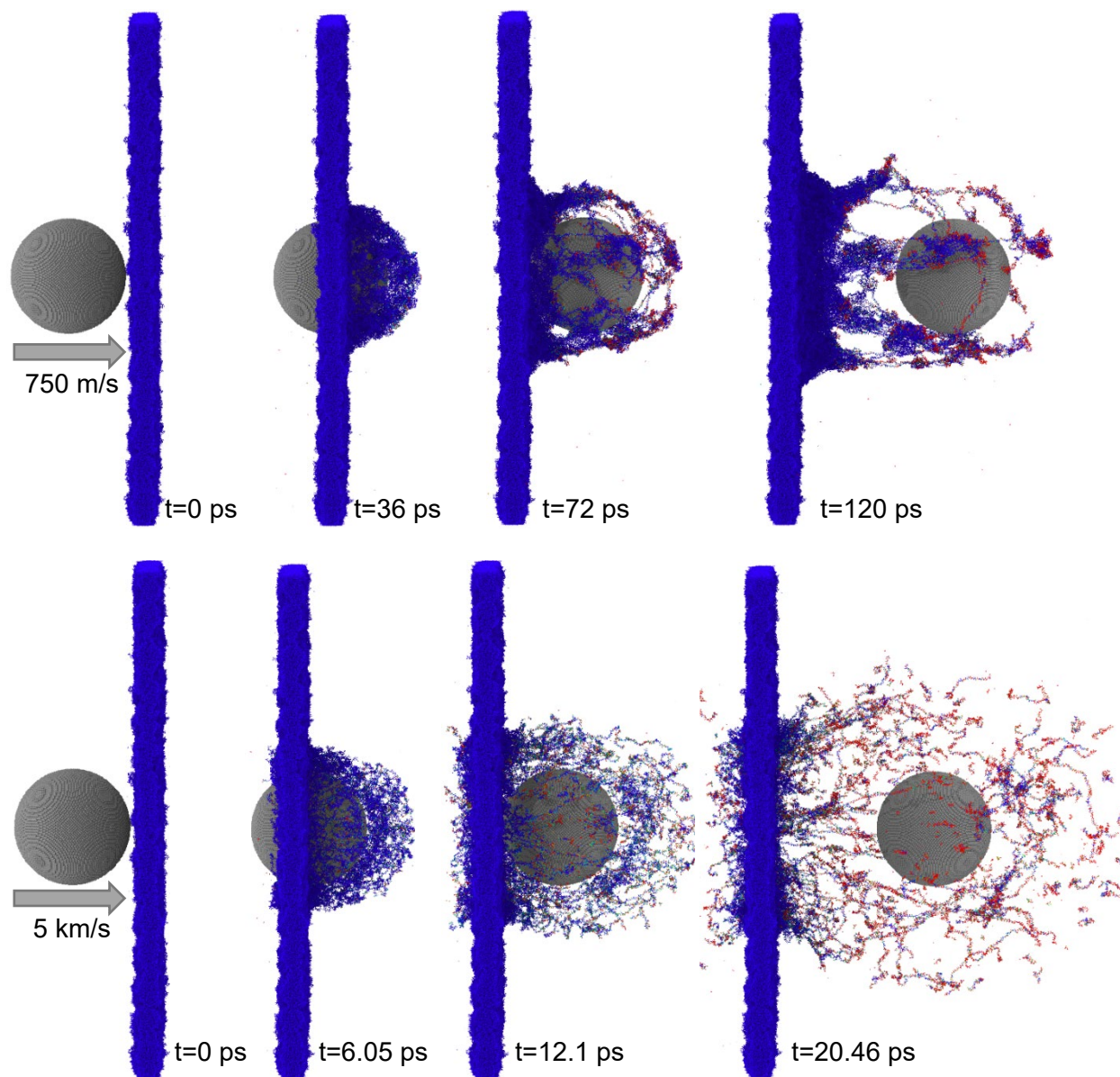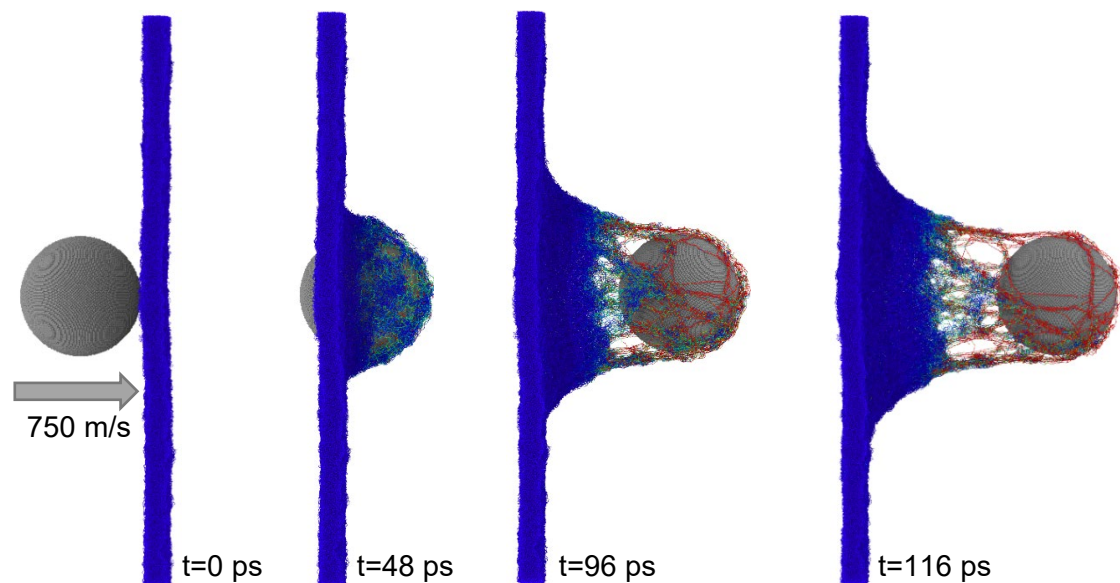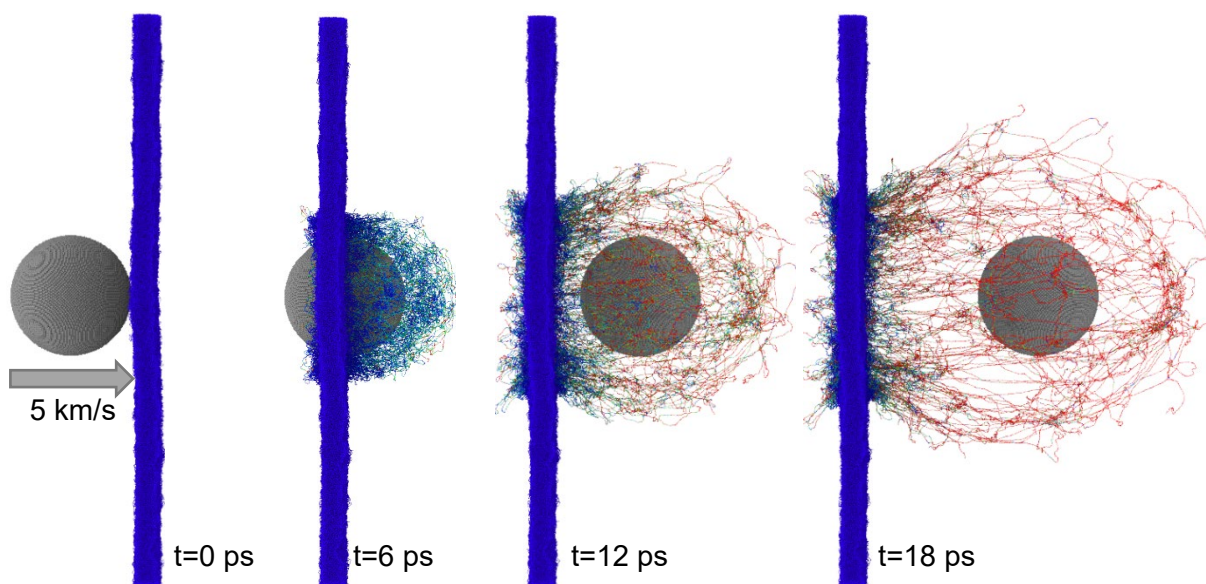

Figure S8. Snapshots of the progression of a ballistic impact event for PS at an impact of 750 m/s and 5 km/s at various time steps during penetration.
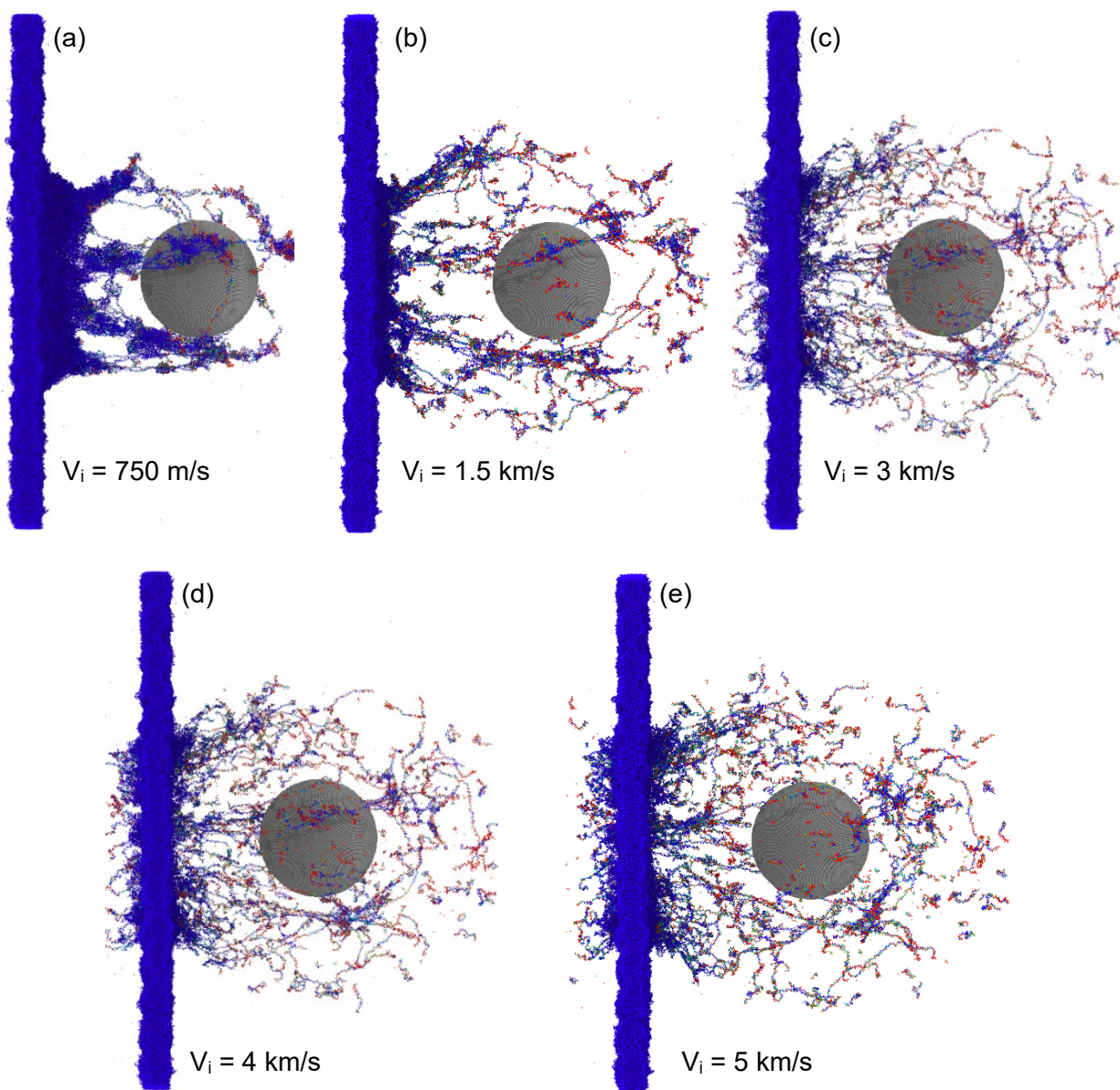
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Figure S9. Snapshots of the progression of a ballistic impact event for PE at an impact of 750 m/s

and 5 km/s at various time steps during penetration.

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(a) V_i = 750 m/s
(b) V_i = 1.5 km/s
(c) V_i = 3 km/s

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(d) V_i = 4 km/s
(e) V_i = 5 km/s

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Figure S10. Snapshots of final ballistic penetration of PS for impact velocities of (a) 750 m/s, (b) 1.5 km/s, (c) 3km/s, (d) 4 km/s, and (e) 5 km/s. Failure transition from chain decohesion and petalling at low impact velocities to fragmentation and chain scission at high impact velocities.
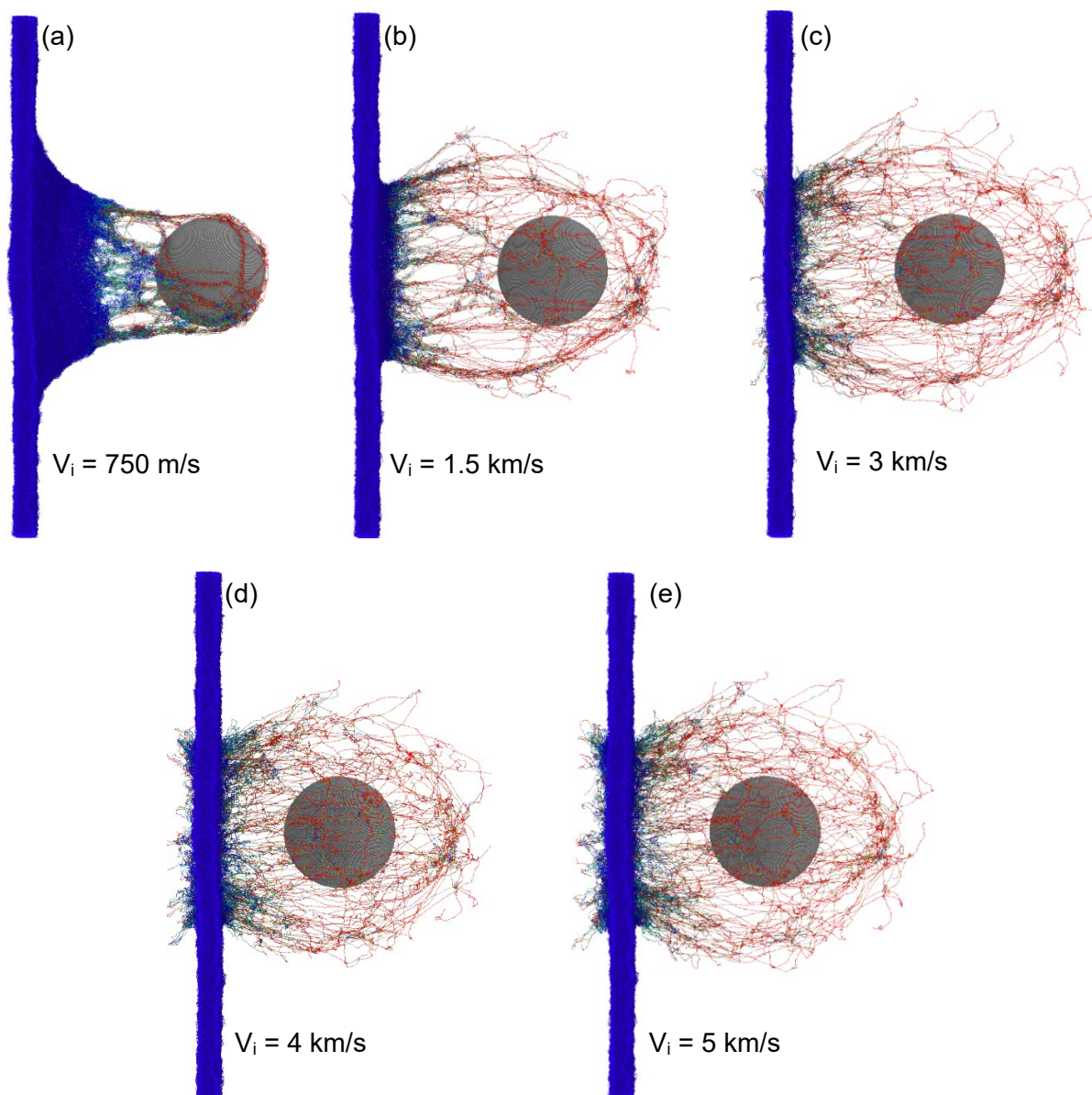
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Figure S11. Snapshots of final ballistic penetration of PE for impact velocities of (a) 750 m/s, (b) 1.5 km/s, (c) 3km/s, (d) 4 km/s, and (e) 5 km/s. Failure transition from void formation and chain pull out at low-impact velocities to fragmentation and disentanglement at high impact velocities.

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